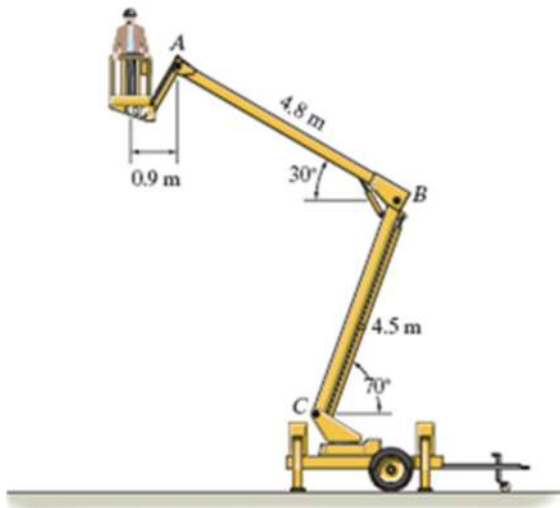


Homework Chapter 3

Problem 3-1: The Snorkel Co. produces the articulating boom platform that can support a weight W . If the boom is in the position shown, determine the moment of this force about points A , B , and C .



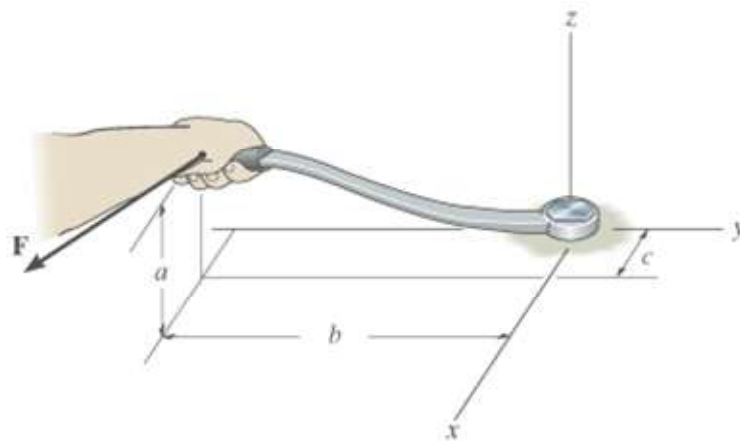
Problem 3-2: The force $\mathbf{F} = \{40\mathbf{i} - 5\mathbf{j} + 5\mathbf{k}\}$ N is applied to the handle of the box wrench. Determine the component of the moment of this force about the z axis which is effective in loosening the bolt.

Given:

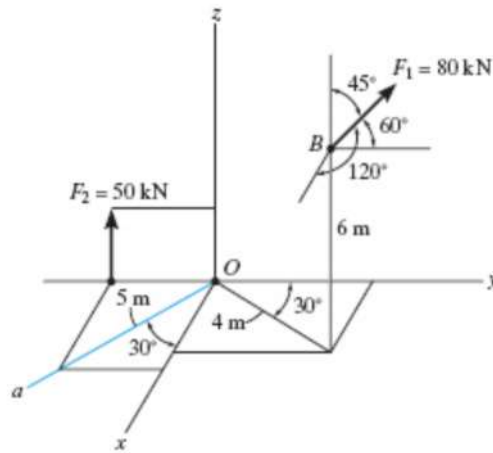
$$a = 75 \text{ mm}$$

$$b = 200 \text{ mm}$$

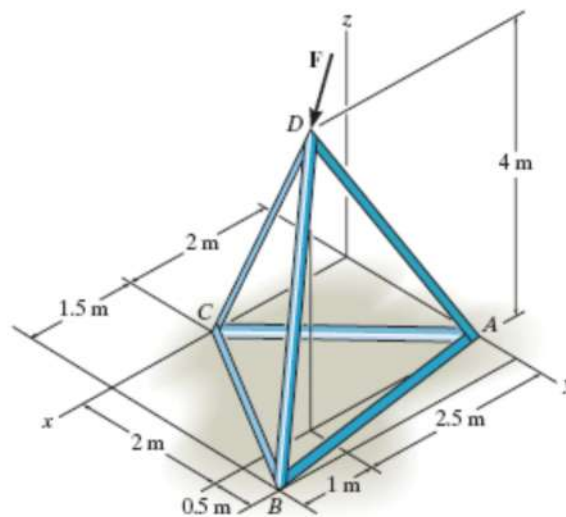
$$c = 50 \text{ mm}$$



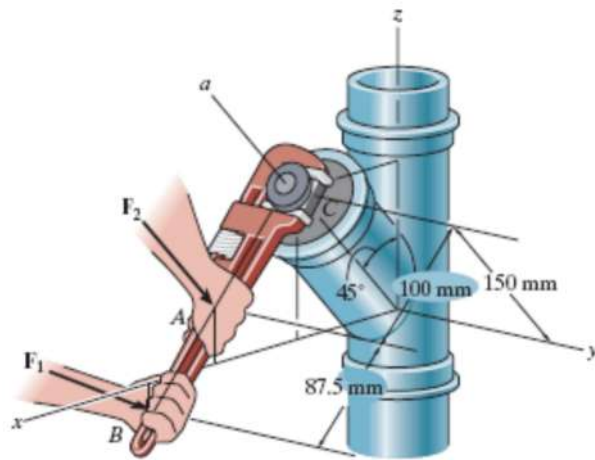
Problem 3-3: Determine the resultant moment of the two forces about the Oa axis. Express the result as a Cartesian vector.



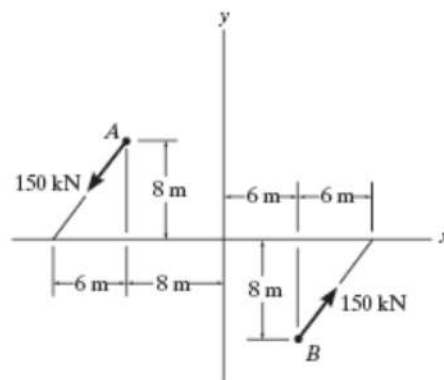
Problem 3-4: Determine the magnitude of the moment of the force $\mathbf{F} = \{50\mathbf{i} - 20\mathbf{j} - 80\mathbf{k}\}$ N about the base line CA of the tripod.



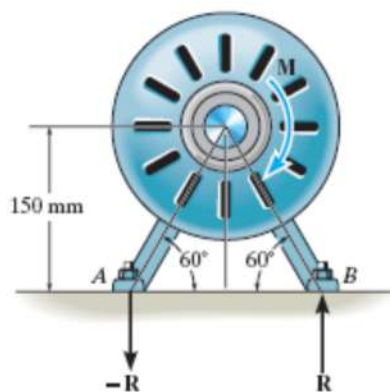
Problem 3-5: Determine the moment of each force acting on the handle of the wrench about the a axis. Take $\mathbf{F}_1 = \{-10\mathbf{i} + 20\mathbf{j} - 40\mathbf{k}\}$ N, $\mathbf{F}_2 = \{15\mathbf{i} + 10\mathbf{j} - 30\mathbf{k}\}$ N.



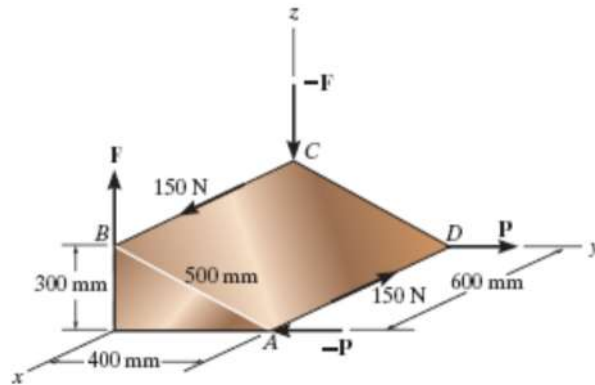
Problem 3-6: Determine the magnitude and sense of the couple moment.



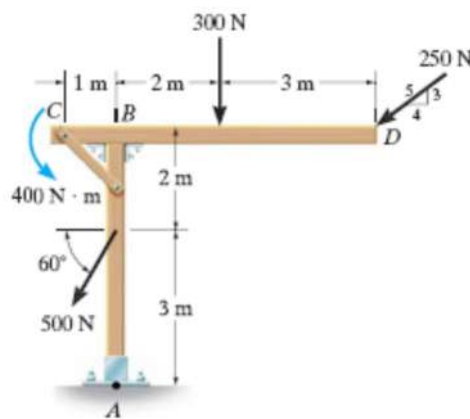
Problem 3-7: A clockwise couple $M = 5$ N.m is resisted by the shift of the electric motor. Determine the magnitude of the reactive forces $\mathbf{R}$ which act at supports A and B so that the resultant of the two couples is zero.



Problem 3-8: If the resultant couple of the three couples acting on the triangular block is to be zero, determine the magnitude of forces $\mathbf{F}$ and $\mathbf{P}$.



Problem 3-9: Replace the loading on the frame by a single resultant force. Specify where its line of action intersects member CD, measured from end C.



Problem 3-10: Handle forces $\mathbf{F}_1$ and $\mathbf{F}_2$ are applied to the electric drill. Replace this system by an equivalent resultant force and couple moment acting at point O . Express the results in Cartesian vector form.

